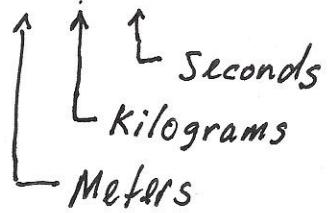


# Units

MKS system



<u>Property</u>	<u>Unit</u>	<u>Other Name for Unit</u>	<u>Abbreviation</u>
length	meter		m
mass	kilogram		kg
time	second		s
force	$\frac{\text{kilogram meter}}{\text{second}^2}$	Newton	N
energy	$\frac{\text{kilogram meter}^2}{\text{second}^2}$	Joule	J

## Motion in 1 Dimension

(2)

$x$  = position of an object

$\Delta x = x_2 - x_1$  = displacement

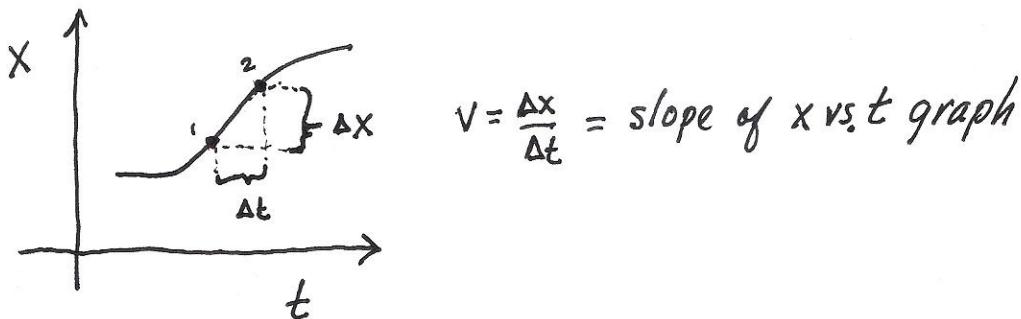
$[\Delta = \text{"change in"}$ ]

$\Delta t = t_2 - t_1$  = time interval

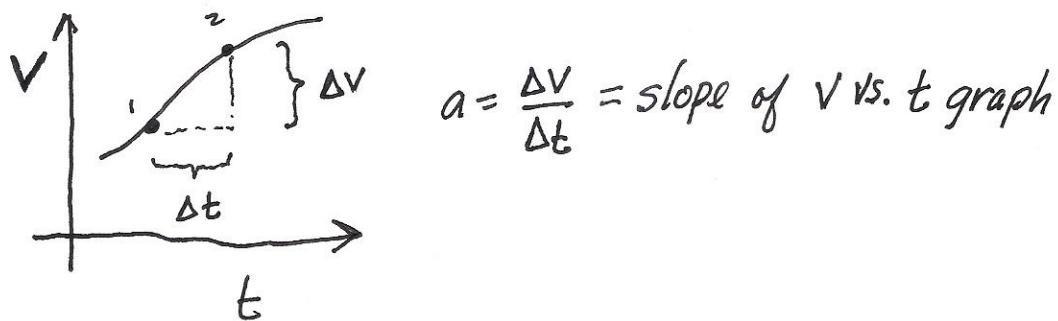
$v$  = velocity =  $\frac{\Delta x}{\Delta t}$

$\Delta v$  = change in velocity =  $v_2 - v_1$

$a$  = acceleration =  $\frac{\Delta v}{\Delta t}$



$$v = \frac{\Delta x}{\Delta t} = \text{slope of } x \text{ vs. } t \text{ graph}$$

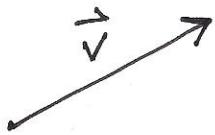


$$a = \frac{\Delta v}{\Delta t} = \text{slope of } v \text{ vs. } t \text{ graph}$$

(3)

## Vectors

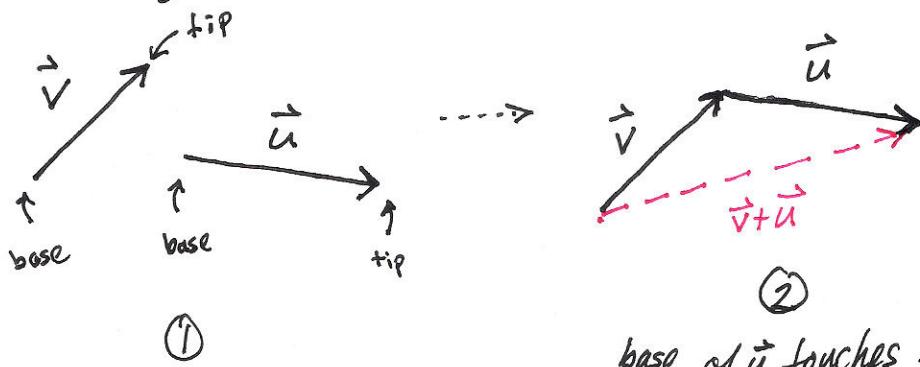
A mathematical entity possessing both a magnitude and a direction



magnitude of vector  $\vec{v}$  is its length.  
direction is direction in which  $\vec{v}$  points

### Addition

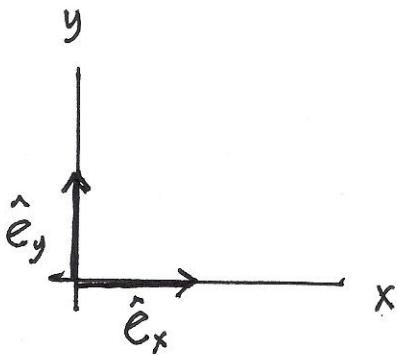
To add  $\vec{v}$  and  $\vec{u}$ , slide  $\vec{u}$  (without changing the direction in which it points) so that its base touches the tip of  $\vec{v}$ .



$\vec{v} + \vec{u}$  (red) is the vector joining the base of  $\vec{v}$  and the tip of  $\vec{u}$ .

$$\vec{v} + \vec{u} = \vec{u} + \vec{v} \text{ for any vectors } \vec{v} \text{ and } \vec{u}.$$

## Unit Vectors



$\hat{e}_x$  = unit vector pointing in x direction

$\hat{e}_y$  = " " " " " y "

$$|\hat{e}_x| = |\hat{e}_y| = 1,$$

where  $|\vec{v}| = v = \text{length of } \vec{v}$

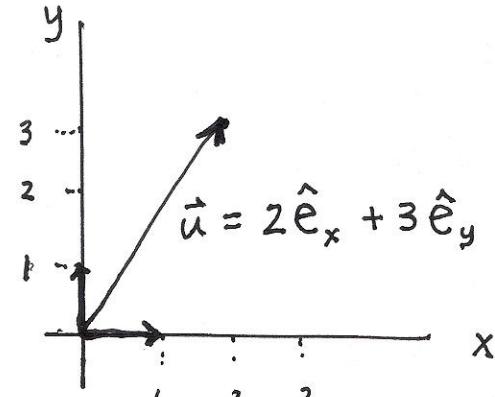
Any vector can be expressed in terms of unit vectors.

$$\vec{v} = v_x \hat{e}_x + v_y \hat{e}_y$$

where  $v_x$  and  $v_y$  are numbers called, respectively, the  $x$  and  $y$  components

of  $\vec{v}$  [Technically,  $v_x \hat{e}_x$

and  $v_y \hat{e}_y$  are the true components]



## Addition Again

$$\vec{v} = v_x \hat{e}_x + v_y \hat{e}_y, \quad \vec{u} = u_x \hat{e}_x + u_y \hat{e}_y$$

$$\vec{v} + \vec{u} = (v_x + u_x) \hat{e}_x + (v_y + u_y) \hat{e}_y$$

$$\text{Example} \quad \vec{v} = -\hat{e}_x + 2\hat{e}_y, \quad \vec{u} = 4\hat{e}_x - 3\hat{e}_y$$

$$\begin{aligned} \vec{v} + \vec{u} &= (-1 + 4) \hat{e}_x + (2 - 3) \hat{e}_y \\ &= 3\hat{e}_x - \hat{e}_y \end{aligned}$$

## Kinematic Equations

Describe motion of objects that undergo a constant acceleration

① Position as a function of time

$$x = x_0 + v_0 t + \frac{1}{2} a t^2$$

$x_0$  = position at  $t=0$        $a$  = constant acceleration

$v_0$  = velocity at  $t=0$

② Velocity as a function of time

$$v = v_0 + at$$

③ Velocity as a function of position

$$v = \sqrt{v_0^2 + 2a(x-x_0)}$$

Derived from ① & ②.

Useful forms ( $x_0=0, v_0=0$ )

$$x = \frac{1}{2} a t^2$$

$$v = a t$$

$$v = \sqrt{2ax}$$

When an object is accelerated by gravity near the surface of the earth,

$$a = g = 9.8 \text{ m/s}^2$$